

Fig. 2 The Structure of the first lineac cavity.

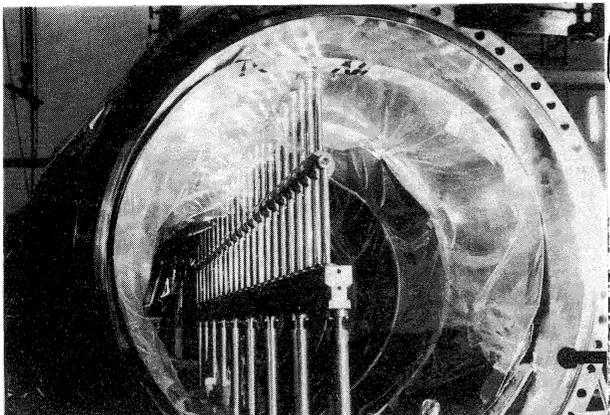


Fig.3 The first lineac cavity photographed from the low energy end.

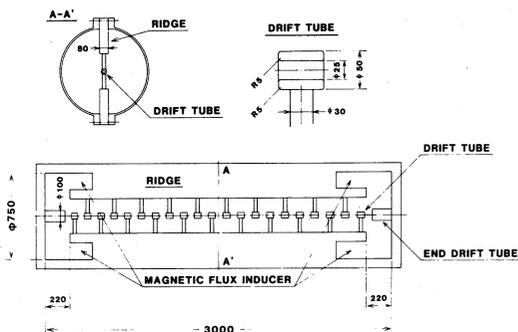


Fig.4 The IH structure of the second accelerating cavity.

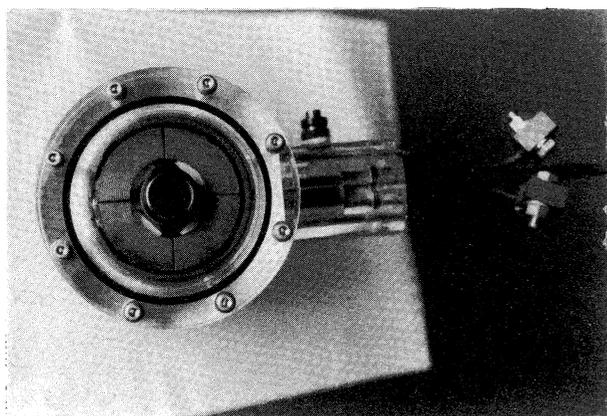


Fig.5 A prototype of quadrupole magnet half lenses equipped in the drift tubes.

pole magnet half lenses. Using spiral plate coils we have observed very stable operation up to a field gradient of 4 kGauss/cm.

Table 1: The main feature of the lineac system

	1st Lineac	2nd Lineac
Injection Energy	0.24 MeV/u	2.5 MeV/u
Output Energy	2.5 MeV/u	3.5 MeV/u
Number of Cells	44	22
Accelerating Frequency	49 MHz	98 MHz
RF Input Power	100 kW max.	50 kW max.
Accelerating Phase	-30°	0°
Species of Ions	All possible ions between Li and Cl	All possible ions between Li and Cl
Beam Current	1 μA electric	0.5 μA electric
Longitudinal Acceptance	90°	100%
Radial Acceptance	70π mm·mrad	50π mm·mrad
Mode of operation	CW	CW
Length of the RF cavity	7 m	3 m
Inner diameter of the RF cavity	1.4 m	0.75 m
Vacuum system	2 x 3000 l·s ⁻¹ turbo-molecular pumps	1 x 1500 l·s ⁻¹ turbo-molecular pump

In the following sections we describe results of experimental and theoretical works for optimization of distribution of the accelerating field in the first cavity.

RESULTS OF SCALE MODEL EXPERIMENTS FOR THE FIRST ACCELERATING CAVITY

Brass scale models were constructed to measure fundamental parameters for the design work. The field distributions were measured by means of the perturbation technique. An equivalent circuit analysis was also performed in parallel with the experimental study.

Equivalent circuit analysis of field distributions

Figure 6-a shows an equivalent circuit for each cell. The ohmic resistance was neglected. The parallel inductance L_t was calculated from the diameter of the cavity. The stem inductance L_s was determined from the length and the diameter of the stems. The capacity C was measured for each drift tube. The series inductance L_l corresponds to the longitudinal component of the surface current in the cavity, and has been extracted from the dispersion relation given as follows:

$$\beta^2 = \omega^2 L_l \left(\frac{C}{1 - \omega^2 L_s C} - \frac{1}{\omega^2 L_t} \right)$$

where ω and β denote the resonant angular frequency and phase constant of the wave, respectively.

Using these parameters we express each cell as a matrix. The whole cavity was simulated by the sequential multiplication of the matrixes.

Accelerating field distribution before adjustment

Figure 6-b shows the result of accelerating-field distribution measurements. The cavity has no short-circuit wings and the inducer was closed by brass plates to interrupt the additional RF magnetic flux. A strong concentration of the field is seen in the low-energy region of the cavity. The curve shows the theoretical prediction obtained by the equivalent circuit analysis.

Effect of the magnetic flux inducer

Figure 6-c shows the effect of the magnetic flux inducer. For simplicity, we have at first mounted only one pair of wings. The angles and length of the wings were 70° and 350 mm, respectively, and were kept constant through this experiment. The theoretical curves reproduce the experimental results very well. The parameters L_t and L_l were changed at the 45th and 46th cell to reflect the effect of the flux inducer into the equivalent circuit analysis.

The field strength was enhanced at the high-energy end. This effect increases with the inducer length. We

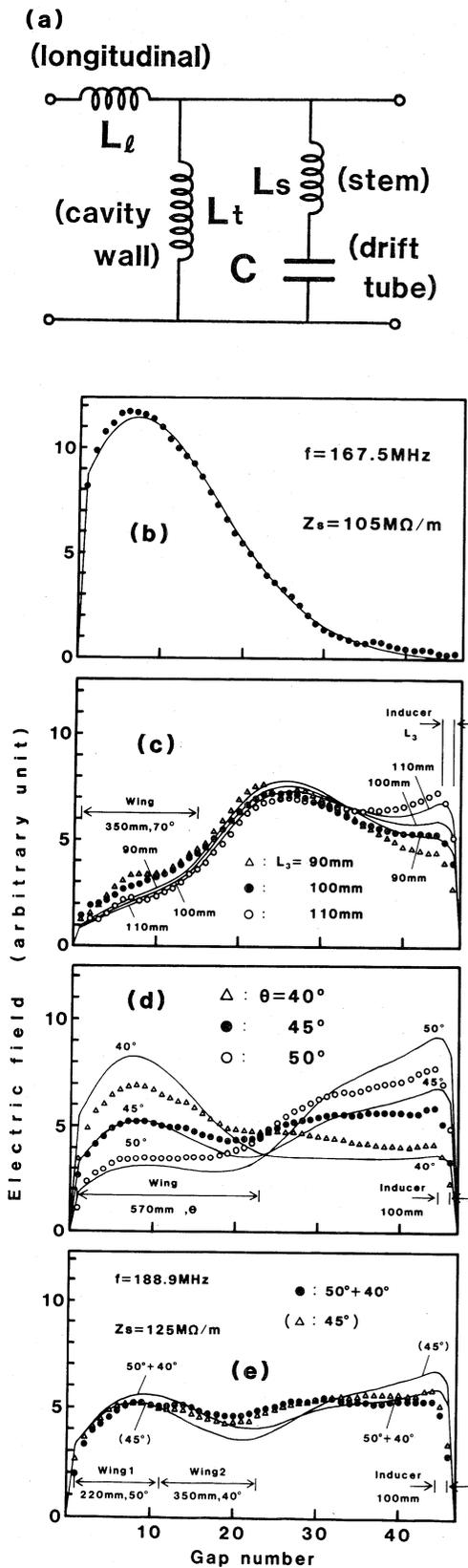


Fig.6 Equivalent circuit for each accelerating cell and variations in the field distribution for various configurations of the tuners. Solid lines are the result of the theoretical calculations.

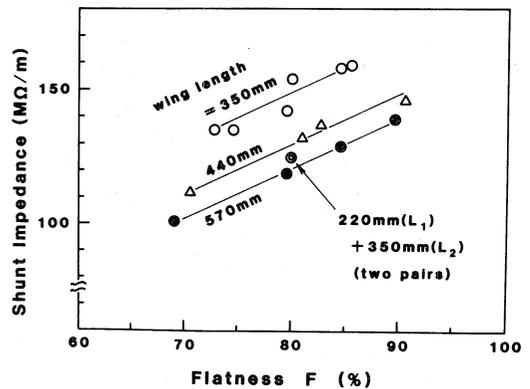


Fig.7 Measured shunt impedances of the model cavity as a function of the flatness F for various wing length.

have chosen 100mm as an optimum length. The optimization of parameters of the short circuit wings was based on this value.

Effect of the short-circuit wing angle

Figure 6-d shows the effect of the wing angle θ on the accelerating field distribution. In this measurement we have had still only one pair of short circuit wings. The field strength in the region of the wings decreases with increase of the wing angle. The curves represent the results of the equivalent circuit analysis. The inductances L_t and L_l in the corresponding region were changed according to the reduction of the cross section.

The field distribution shows a dent at the interface between the region with the wings and that without wings.

In order to avoid the dent, we have introduced one more pair of wings. The result is shown in Fig.6-e. The dent has disappeared and an almost uniform field distribution was obtained.

Influence of the tuners on shunt impedance

In order to investigate the effect of the form of field on the RF power consumption, a shunt impedance of the model cavity was deduced from the perturbation measurements for each tuner configuration. For a quantitative estimations of the shape of the distributions, we defined "flatness" F as follows :

$$F \equiv 1 - \frac{\sigma}{\bar{V}}$$

where \bar{V} and σ denote the mean value and the standard deviation of the gap voltages, respectively. This value was determined for each configuration of the tuners.

The measured shunt impedances are plotted in Fig.7 in terms of the flatness. The result shows that the shunt impedance increases with the flatness F for each wing length. Since the flatness obtainable by this method is limited to at most 90%, the extrapolation of the curves to $F=100\%$ has no meaning.

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